

# Semi-automated pipeline to produce customizable tactile maps of street intersections for people with visual impairments

Yuhao Jiang<sup>a</sup>, María-Jesús Lobo<sup>a</sup>, Sidonie Christophe<sup>a</sup>, Christophe Jouffrais<sup>b</sup>

<sup>a</sup> LASTIG, Univ Gustave Eiffel, ENSG, IGN, F-94160 Saint-Mande, France, [yuhao.jiang@ensg.eu](mailto:yuhao.jiang@ensg.eu), [Maria-Jesus.Lobo@ign.fr](mailto:Maria-Jesus.Lobo@ign.fr), [Sidonie.Christophe@ign.fr](mailto:Sidonie.Christophe@ign.fr)

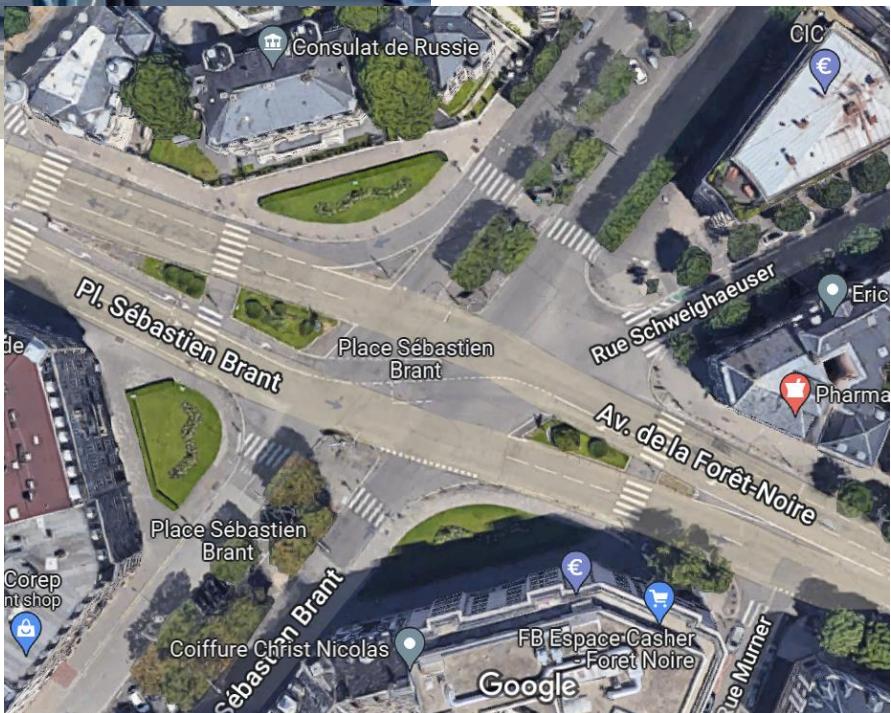
<sup>b</sup> IRIT, University of Toulouse, Toulouse, France, [christophe.jouffrais@irit.fr](mailto:christophe.jouffrais@irit.fr)

June 2023

# Context: assisting street crossing with tactile maps

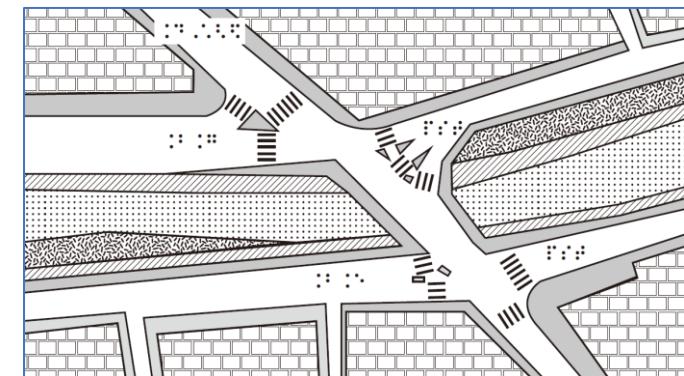
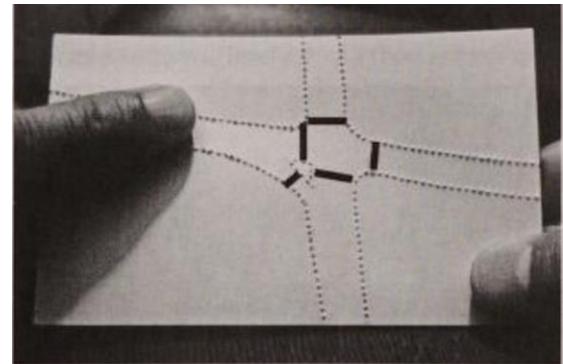


Fazzi, D. L. , & Barlow, J. M. (2017).

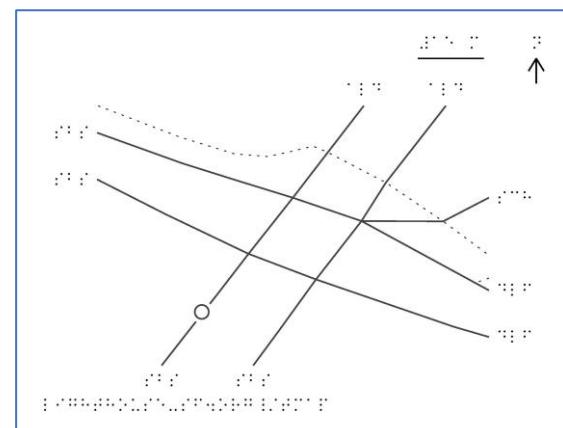


## Handmade / toolkits

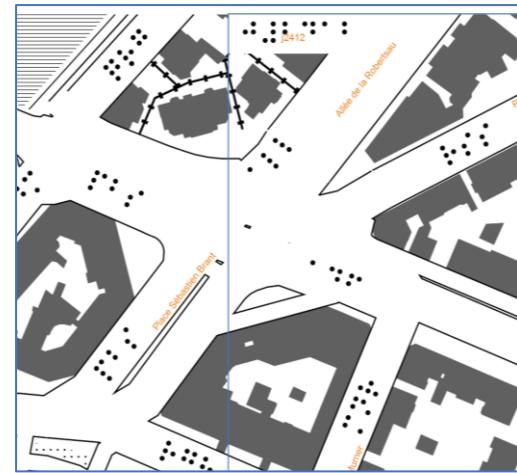
Townki



## Automated services



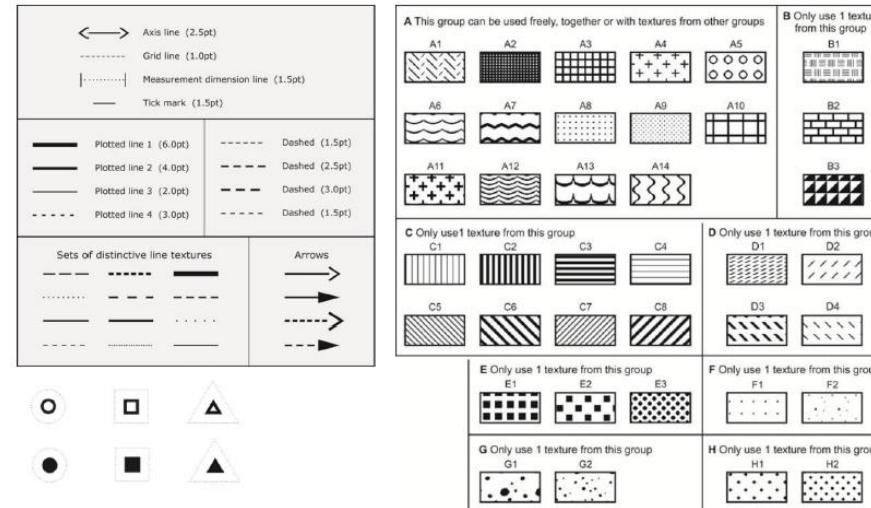
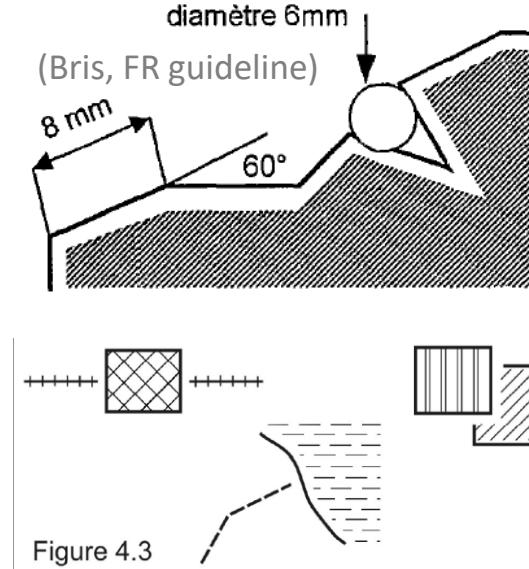
TMAP



Mapy.cz

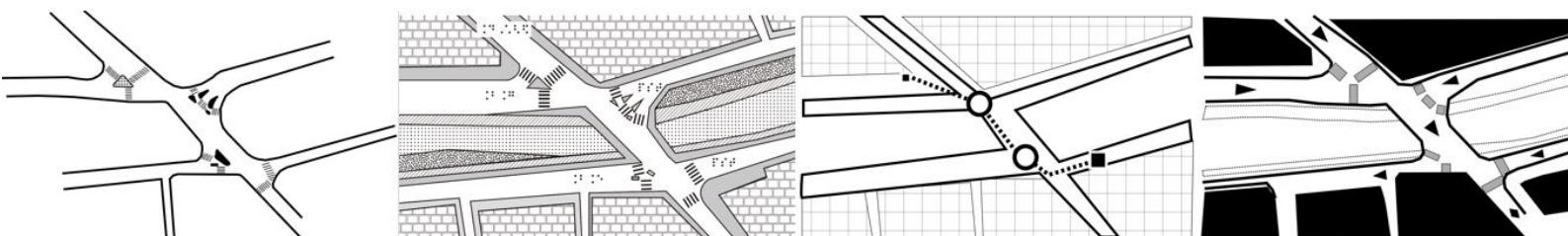
# Designing a tactile map and automation: constraints, flexibilities, and diversity

## Tactile graphics guidelines give the “basics”



The N.S.W. Tactile and Bold Print Mapping Committee. (2006).  
Braille Authority of North America (2010)

## Practice is always flexible and diverse



IRIT / University of Toulouse

## Tactile graphics guidelines say,

- Line width
- Point size
- Gap requirements
- Reduce detail to reduce clutter
- Available symbols
- Layouts on standard page
- ...

## *They don't say,*

- What objects to choose
- Level of detail (“how much is too much”)
- Conflict solving strategies
- Associating symbol with objects
- Bigger / smaller pages
- ...

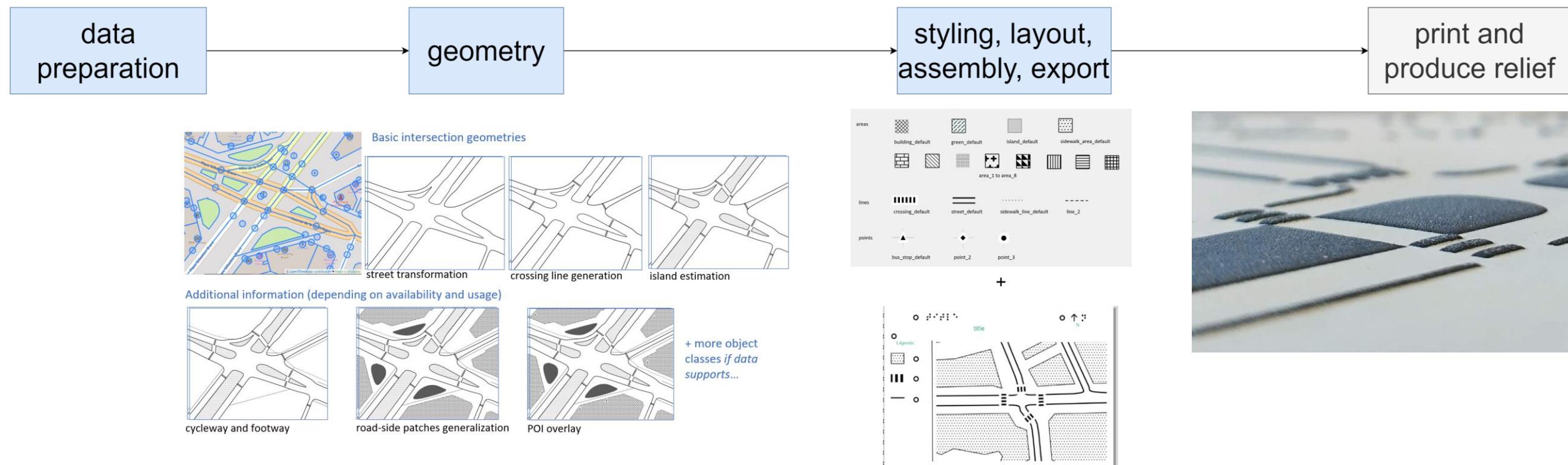
**“ it depends on the person ”**

# A semi-automated pipeline: from OpenStreetMap to swell paper prints

## parameters:

- map basics (location / size / scale)
- object choice
- tactile graphic params (line width, gaps etc)
- styling choices
- specific geometry processing choice

Carto process + tactile adaptions + possibilities to customize





pedestrian crossing  
(line)

pedestrian crossing  
(point)

lane count estimation

OSM file  
inspection,  
curation

param.json  
processing extents

bus stop (point)

sidewalks (line or area)

buildings / green areas

street (line)

displacement  
• map extent  
• scale  
• point size  
• point gap  
• overlay mode

simplification  
and displacement  
• scale  
• line gap  
• line width

dilation-erosion-simplification  
• line-area gap  
• area gap  
• min area  
• level of detail

bus stops

sidewalks (line or area)

generalized patches

street (area)

smoothing, to line

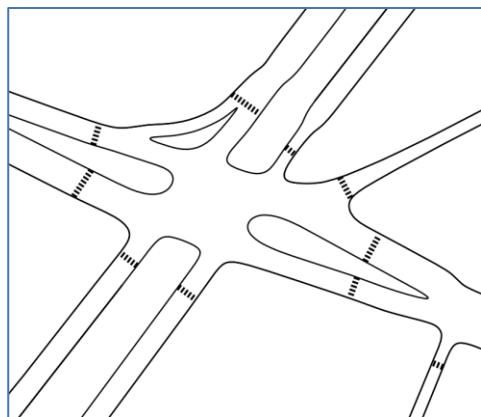
street boundary / curb  
(line)

traffic island (area)

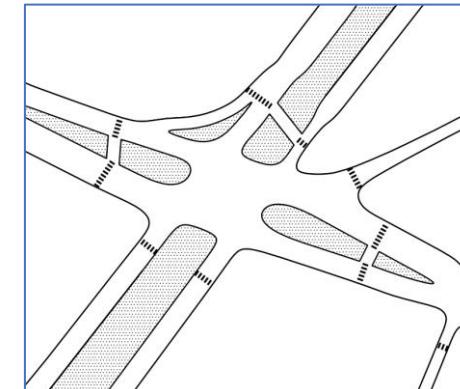
- area gap
- min area

attribute  
input

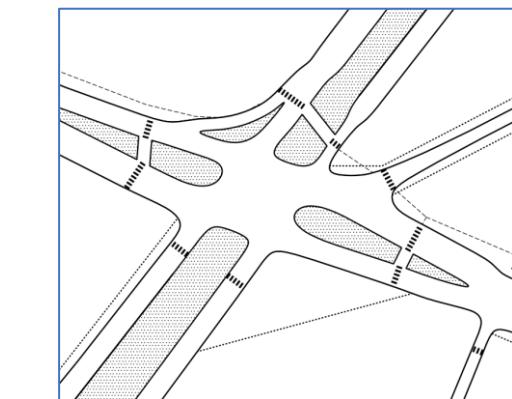
traffic islands with splits  
(area)



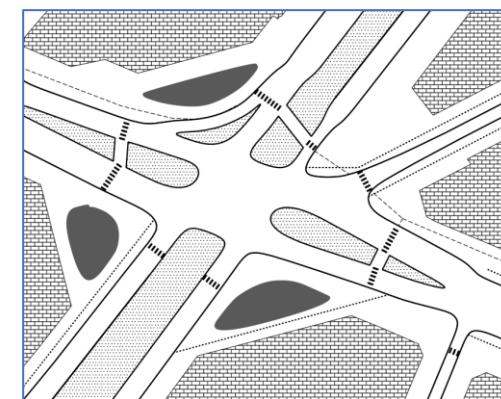
## Street and crossing transformation



## Island estimation

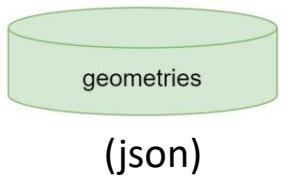


## Sidewalks

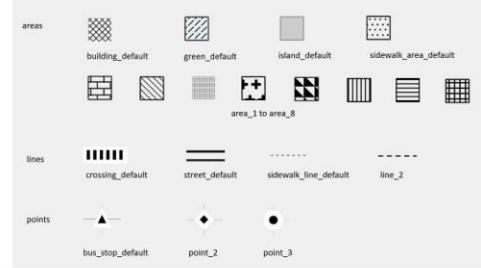


## Patches generalization

## Map export

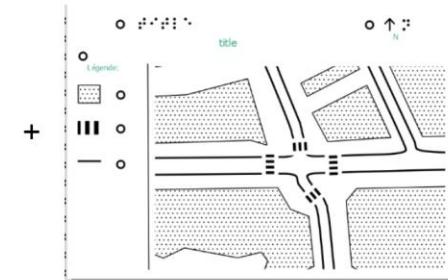


+

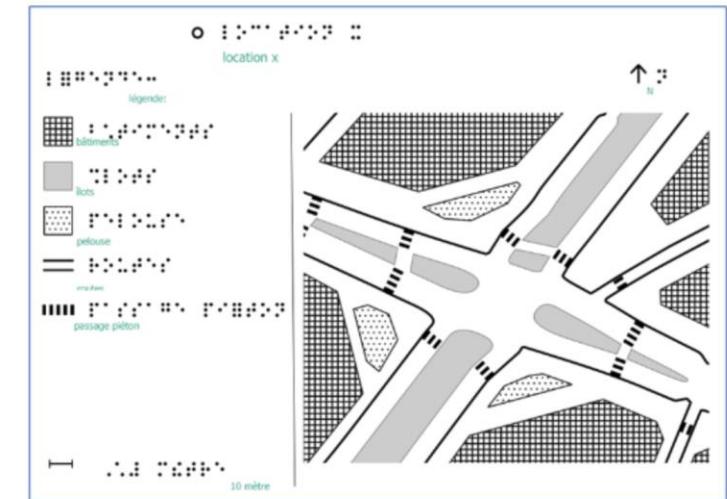


param.json

styles (qml)

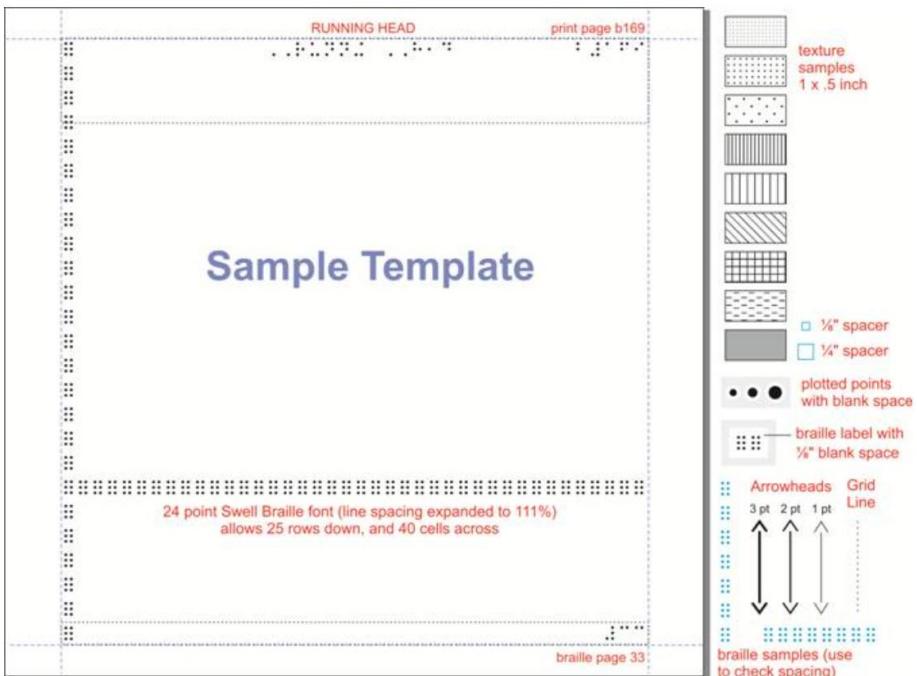


templates (qpt)



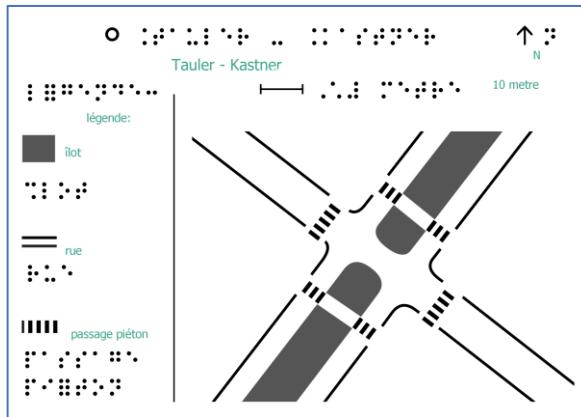
map to print on swell paper (pdf)

A3 / A4 / A5 + “no braille”  
templates, (based on  
guidelines + page specific  
adaptations)

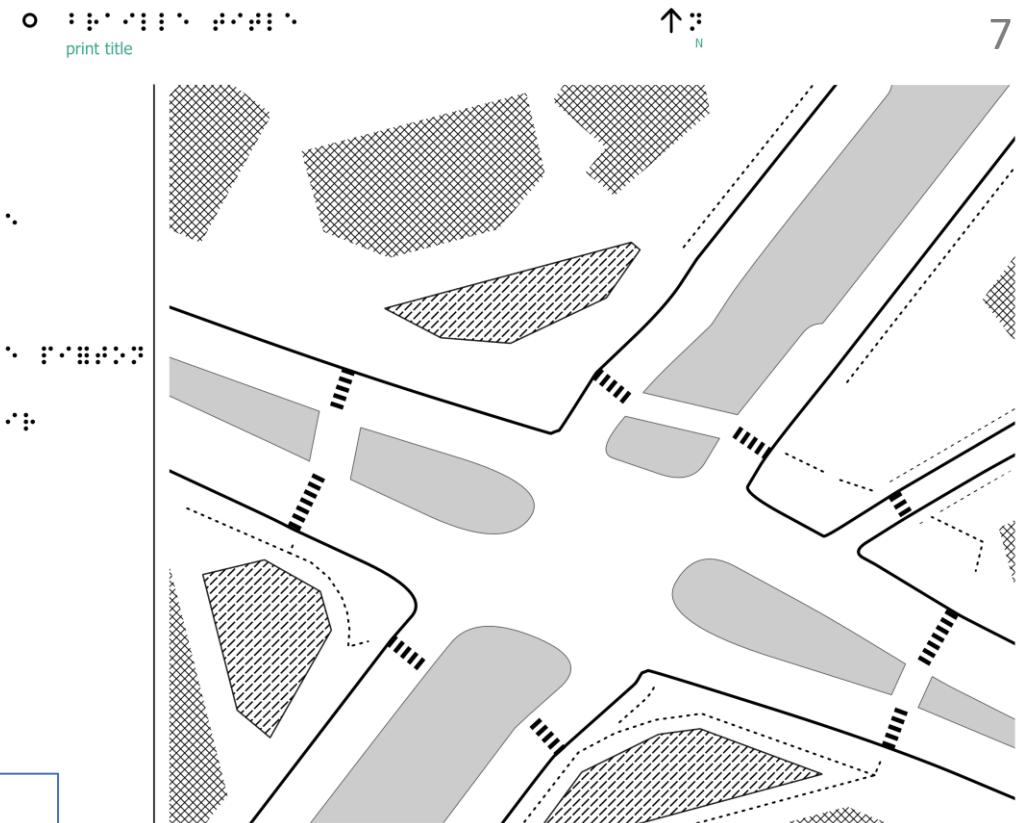
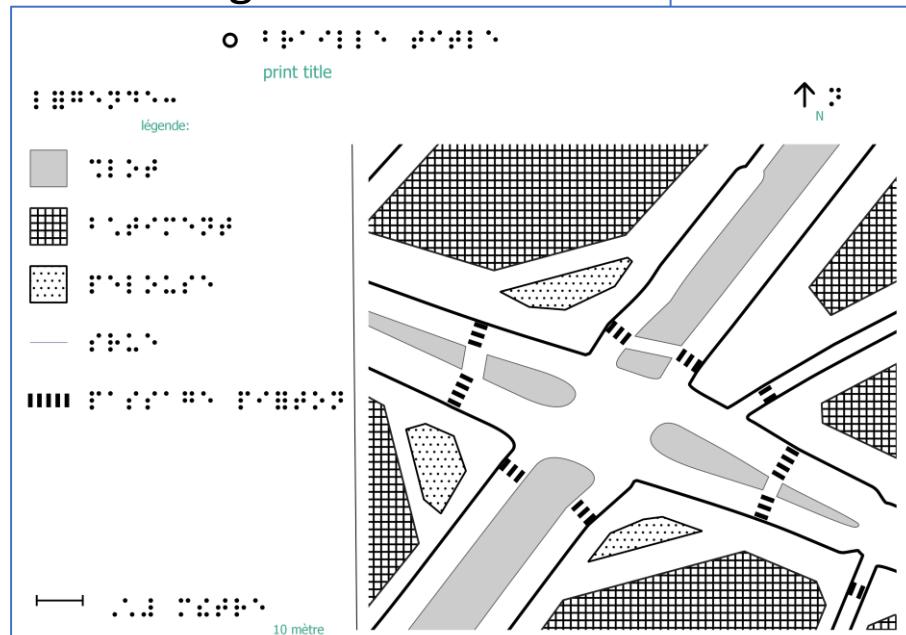


BANA (2010)

# Maps for prints: 3 sizes with flexibilities



**A4 1:1000**  
Balancing info & size



**A3 1:500**  
Space for details and exploration



# “Future” work: from making the maps to evaluating them

## Map being “correct” / “acceptable”

Evaluation aspects:

- **Graphics:** is the map design acceptable? / how do you measure the clutter of a tactile map?
- **Printing & production:** will it eventually feel like what the design intents to?
- **Automated evaluations**
- **Tactile transcribers**
- Mobility instructors

## Map being “usable”

Use contexts:

- with instructors / independently
- Evaluation aspects:
- **Reading the map**
  - Applying the map in reality ( $\Delta$ )
  - Mobility instructors
  - **PVIs**

